

# Conservative discontinuous Galerkin discretizations of the 2D incompressible Euler problem

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# Abstract

Discontinuous Galerkin (DG) methods provide local high-order adaptive numerical schemes for the solution of convection-diffusion problems. They combine the advantages of finite element and finite volume methods. In particular, DG methods automatically ensure the conservation of all first-order invariants provided that single-valued fluxes are prescribed at inter-element boundaries. For the 2D incompressible Euler equation, this implies that the discretized fluxes globally obey Gauss' and Stokes' laws exactly, and that they conserve total vorticity. Combining a continuous Galerkin (CG) solution of Poisson's equation with a central DG flux for the convection term leads to an algorithm that conserves the principal two quadratic invariants, namely the energy and enstrophy. Here, we present a discretization that applies the DG method to Poisson's equation as well as to the vorticity equation while maintaining conservation of the quadratic invariants. **Acknowledgements** This work was

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# Discontinuous Galerkin: A local conservative high-order adaptive method

- The motivation for the discontinuous Galerkin (DG) method is to maintain locality while achieving high-order accuracy on unstructured meshes
  - ▶ Unstructured for geometric flexibility
  - ▶ High order for accuracy
  - ▶ Local for parallel efficiency
  - ▶ Automatic element-wise conservation of first-order invariants

	Complex geometries	High-order accuracy and <i>hp</i> -adaptivity	Explicit semi-discrete form	Conservation laws	Elliptic problems
FDM	✗	✓	✓	✓	✓
FVM	✓	✗	✓	✓	(✓)
FEM	✓	✓	✗	(✓)	✓
DG-FEM	✓	✓	✓	✓	(✓)

## Previous conservative DG algorithms

- Liu and Shu [1] have proposed a DG discretization of 2D Euler using a **Continuous Galerkin (CG) algorithm to invert Poisson's equation**. Their algorithm can conserve enstrophy as well as energy, but allowing some enstrophy decay improves the robustness of the scheme.
- Einkemmer and Wiesenberger [2] have extended the Arakawa method to apply to a DG discretization but this only works for periodic boundary conditions.
- In this poster, we examine the conservation of quadratic invariants for the 2D Euler problem when **both Poisson's equation and the vorticity equation** are solved using the DG method.

# Governing equations

- The system describing incompressible and inviscid 2D flows is

$$\partial_t U = -\mathbf{e}_z \cdot (\nabla \phi \times \nabla U); \quad (1)$$

$$U = \nabla^2 \phi; \quad (2)$$

$$\phi = \phi_b \text{ on } \partial\Omega, \quad (3)$$

where  $\phi_b$  is given and  $\partial\Omega$  is the boundary of the domain  $\Omega$ .

- This is the archetype of a class of nonlinear fluid problems that includes many multi-scale dynamical systems important in plasma physics.

# Conservation properties of the incompressible 2D Euler model

- The 2D Euler model conserves the following **energy**:

$$H(\phi) = \frac{1}{2} \int d^2x (\nabla\phi)^2. \quad (4)$$

- In addition to conserving  $H$ , it also conserves the moment and a family of Casimir invariants,

$$\mathbf{M} = \int d^2x \mathbf{x}U. \quad (5)$$

$$G(\phi) = \int d^2x g(U), \quad (6)$$

- The choice  $g(U) = U^2$  corresponds to the **enstrophy**.

## Weak formulation

- To discretize the equations, we introduce  $\mathcal{E} = \nabla\phi$ .
- In terms of this auxiliary variable  $\mathcal{E}$ , Poisson's equation is

$$U = \nabla \cdot \mathcal{E}; \quad (7)$$

$$\phi = \phi_b(\mathbf{x}) \text{ on } \partial\Omega. \quad (8)$$

- The weak formulation of the problem is:

$$\int_K d^2x w U_h = \int_{\partial K} ds w \hat{\mathcal{E}} \cdot \mathbf{n} - \int_K d^2x \mathcal{E}_h \cdot \nabla_h w; \quad (9)$$

$$\int_K d^2x \xi \cdot \mathcal{E}_h = \int_{\partial K} ds \hat{\phi} \xi \cdot \mathbf{n} - \int_K d^2x \phi_h \nabla_h \cdot \xi. \quad (10)$$

Here  $\mathbf{n}$  is the outward unit normal to the boundary  $\partial K$  of the element,  $\hat{\mathcal{E}}$  and  $\hat{\phi}$  are the **numerical fluxes** across the element boundaries



# Gauss' law

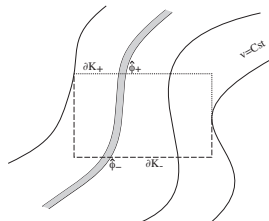
- For  $w = 1$  Eq. (9) becomes

$$\int_K d^2x U_h = \int_{\partial K} ds \hat{\mathcal{E}} \cdot \mathbf{n}, \quad (11)$$

- Note that for a plasma the vorticity is proportional to the polarization **charge density**, so that the above identity expresses the **element-wise** applicability of Gauss' law.
- If the numerical flux is conservative, Gauss' law may be extended to macroscopic volumes by summing over elements:

$$\int_{\Omega} d^2x U_h = \int_{\partial\Omega} ds \hat{\mathcal{E}} \cdot \mathbf{n}, \quad (12)$$

## Stokes' law



- Taking  $\xi = \mathbf{e}_z \times \nabla_h v$  in Eq. (10), we have  $\nabla \cdot \xi = 0$ .
- Consider a curvilinear coordinate system  $(u(x, y), v(x, y))$ .
- The length element along lines of constant  $v$  is
 
$$dl = du / \mathbf{e}_\ell \cdot \nabla_h u = |\nabla_h v| \mathcal{J}(v, u) du.$$

- Changing coordinates in Eq. (10), there follows

$$\int_K dv dl \mathbf{e}_\ell \cdot \boldsymbol{\varepsilon}_h = \int_{\partial K^+} dv \hat{\phi} - \int_{\partial K^-} dv \hat{\phi}.$$

For single-valued  $\hat{\phi}$ , this can again be extended to macroscopic volumes by summing over  $K$ s.

# Primal form

- An alternative to solving Eqs. (9)-(10) is to eliminate  $\mathcal{E}$ , obtaining a variational equation for  $\phi$  alone in terms of the **primal form**  $\mathcal{L}_\Omega$  [3]

$$\mathcal{L}_\Omega(\phi_h, \mathbf{w}) = - \int_K d^2x w U_h, \quad (13)$$

where

$$\begin{aligned} \mathcal{L}_K(\phi_h, \mathbf{w}) = & \int_K d^2x \nabla_h \phi_h \cdot \nabla_h \mathbf{w} \\ & - \int_{\partial K} ds [(\hat{\phi} - \phi_h) \mathbf{n} \cdot \nabla_h \mathbf{w} - w \hat{\mathcal{E}} \cdot \mathbf{n}] \end{aligned} \quad (14)$$

# Interior Penalty method

- The classic IP method corresponds to the choice of fluxes

$$\hat{\phi} = \{\phi_h\} \text{ on } \Gamma_0 \text{ and } \hat{\phi} = 0 \text{ on } \partial\Omega; \quad (15)$$

$$\hat{\mathcal{E}} = \{\nabla_h \phi_h\} - \alpha_j([\![\phi_h]\!]]) \text{ on } \Gamma; \quad (16)$$

where  $\alpha(x) = \alpha_j x$  on each edge  $e_j$  “penalizes” the discontinuities.

- The corresponding primal form is symmetric,

$$\begin{aligned} \mathcal{L}_\Omega(\phi_h, \mathbf{w}) &= \int_\Omega d^2x \nabla_h \phi_h \cdot \nabla_h \mathbf{w} - \int_\Gamma ds [\![\mathbf{w}]\!] \cdot \alpha([\![\phi_h]\!]]) \\ &\quad - \int_\Gamma ds ([\![\phi_h]\!] \cdot \nabla_h \{\mathbf{w}\} + [\![\mathbf{w}]\!] \cdot \nabla_h \{\phi_h\}). \end{aligned} \quad (17)$$

# Kinetic energy

- We obtain a numerical kinetic energy by taking the time derivative of Poisson's equation (13) and replacing the test function  $w$  by  $\phi$ :

$$\frac{1}{2} \frac{d}{dt} \mathcal{L}_\Omega(\phi_h, \phi_h) = - \int_\Omega d^2x \phi_h \partial_t U_h \quad (18)$$

- The above shows that  $\mathcal{L}_\Omega(\phi_h, \phi_h)$  changes at a rate determined by the work done by the convection of vorticity.
- We will show that this is small and can be made to vanish.

## Weak form of the vorticity equation

- The weak form of the vorticity equation is

$$\int_K d^2x v \partial_t U_h = \int_{\partial K} ds v \widehat{U} \mathcal{E}_h \cdot \mathbf{t} - \int_K d^2x U_h (\mathcal{E}_h \times \mathbf{e}_z) \cdot \nabla_h v, \quad (19)$$

where  $v$  is a test function,  $\mathbf{t} = \mathbf{e}_z \times \mathbf{n}$  and  $\widehat{U} \mathcal{E}_h$  is the numerical flux at element boundaries.

- When using the primal form of Poisson's equation, we must eliminate  $\mathcal{E}_h$ :

$$\begin{aligned} \int_K d^2x v \partial_t U_h = & \int_{\partial K} ds (v \widehat{U} \mathcal{E}_h + \hat{\phi} U_h \nabla_h v) \cdot \mathbf{t} \\ & + \int_K d^2x \phi_h (\nabla U_h \times \mathbf{e}_z) \cdot \nabla_h v, \end{aligned} \quad (20)$$

# Energy conservation

- Replacing  $w$  by  $\phi$  in the weak form of the vorticity equation and integrating by parts yields the following form for the work done by vorticity convection:

$$\int_{\Omega} d^2x \phi_h \partial_t U_h = \int_{\Gamma} ds (\mathbf{n} \cdot \llbracket \phi_h \rrbracket) \mathbf{t} \cdot (\widehat{U\mathcal{E}}_h - \{U_h \nabla_h \phi_h\}) - \int_{\Gamma^0} ds (\hat{\phi} - \{\phi_h\}) \llbracket \mathbf{e}_z \times U_h \nabla_h \phi_h \rrbracket$$

- Energy is thus conserved by the following choice of flux:

$$\widehat{U\mathcal{E}}_h = \{U_h \nabla_h \phi_h\} \quad (21)$$

# Enstrophy conservation

- Replacing  $w$  by  $U$  in the weak form of the vorticity equation and integrating yields

$$\frac{1}{2} \frac{d}{dt} \int_K d^2x U_h^2 = \int_{\partial K} ds [U_h(\mathbf{t} \cdot \widehat{U}\mathcal{E}_h) + \hat{\phi}(\mathbf{t} \cdot \nabla_h U_h^2/2)]$$

- We next integrate the last term by parts. After summing over the elements, we find

$$\frac{1}{2} \frac{d}{dt} \int_K d^2x U_h^2 = \int_{\Gamma} ds (\mathbf{n} \cdot \llbracket U_h \rrbracket) \mathbf{t} \cdot (\widehat{U}\mathcal{E}_h - \{U_h\} \nabla_h \hat{\phi}) \quad (22)$$

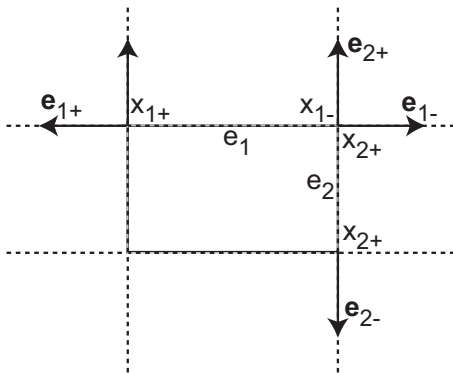
where the  $\nabla_h \hat{\phi}$  contains  $\delta$ -function vertex-contributions from the discontinuities of  $\hat{\phi}$ .



# Illustration of vertex contributions

- The following choice of flux conserves enstrophy:

$$\widehat{U\mathcal{E}}_h = \{U_h\} \nabla_h \hat{\phi} \quad (23)$$



# Summary




- Using DG for **Poisson's** as well as the vorticity equation, it is possible to conserve enstrophy or vorticity but not both.
- The Poincaré inequality implies that the enstrophy bounds the kinetic energy:

$$\int_{\Omega} d^2x (\nabla\phi)^2 < \int_{\Omega} d^2x U^2.$$

It follows that conserving enstrophy will ensure stability of both velocity and vorticity.

- Similar techniques can be used to construct DG formulations of the 2D Navier-Stokes equations with the desired stability and conservation properties.
- Numerical implementation is underway.

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