2004 International Sherwood Theory Conference

Formation and Instability of Phase Space Structures

D.Yu. Eremin and H.L. Berk



Institute for Fusion Studies, the University of Texas at Austin

Outline

- Formation of nonlinear phase-space structures.
- Adiabatic evolution of the structures.
- Stability analysis of the structures.
- Mutual interaction between multiple structures.

Nonlinear Evolution of Waves due to Weak Instabilities

- Resonant particles destabilize waves a plasma can support.
- System is close to the linear instability threshold, where kinetic drive = background dissipation.
- Spatial structure of waves remains unchanged.
- Dominant nonlinearity is caused by interaction with resonant particles

Formation of Phase Space Structures (Experimental Data)

Terrella experiment



Columbia University, Mauel et. al.

TAE modes in MAST



Culham Laboratory, U. K. courtesy of Mikhail Gryaznevich

Signature for Formation of Phase Space Structures (Theory)

 $\gamma_L - \gamma_d \ll \gamma_L$ [Berk, Breizman, and Pekker, Plasma Phys. Rep. (1997)]

$$\frac{d\tilde{A}}{dt} = \tilde{A} - \frac{1}{2} \int_{0}^{t/2} d\tau \tau^{2} \int_{0}^{t-2\tau} d\tau_{1} G(\tau, \tau_{1}) \tilde{A}(t-\tau) \tilde{A}(t-\tau-\tau_{1}) \tilde{A}^{*}(t-2\tau-\tau_{1})$$

Explosive self-similar solution for small collisional effects



Explosive Solution



Formation of "Holes" and "Clumps"



Frequency Sweeping of Nonlinear Phase Space Structures



Slow Evolution of the Structures

Slowly changing wave properties: $\max\left(\frac{d\delta\omega}{dt}, \frac{d\omega_b}{dt}\right) \ll \omega_b^2$

Adiabatic invariants for description of the evolution of the trapped particle distribution function

$$J = \frac{1}{2\pi} \oint d\xi p_{\xi} = \frac{1}{\pi} \int_{-\xi_{\text{max}}}^{\xi_{\text{max}}} \left[2(E + \omega_b^2 \cos(\xi)) \right]^{1/2} = const \quad \Longrightarrow F(J) = const$$

+ equations for the mode phase and amplitude

Self-consistent adiabatic analysis, stable evolution of waves and particles

Description of Adiabatic Evolution

Evolution of the mode's normalized trapping frequency Ω_b in terms of normalized frequency shift Ω is governed by

$$\Omega_{b} = 1 - \frac{1}{\Omega} \int_{0}^{1} dI Q(I) F_{T}(\Omega_{b}I) \qquad J \sim \Omega_{b}I$$
$$0 \le I \le 1$$

$$Q(I) = 3 \frac{\int_0^{\xi_{\text{max}}} d\xi \cos \xi / [E + \cos \xi]^{1/2}}{\int_0^{\xi_{\text{max}}} d\xi / [E + \cos \xi]^{1/2}}$$

- Ω normalized frequency shift
- Ω_{h} normalized trapping frequency

Problems in Adiabatic Description

Differentiating
$$\Omega_b = 1 - \frac{1}{\Omega_b} \int_0^1 dIQ(I) f_T(\Omega_b I)$$
, one obtains:

$$\frac{\frac{d\Omega}{d\Omega_b}}{\frac{d\Omega_b}{\Omega_b}} = \frac{\Omega H_T(\Omega, \Omega_b)}{1 - \Omega_b}$$

$$H_T(\Omega, \Omega_b) = 1 + \frac{1}{\Omega_b} \int_0^1 dI f_T'(\Omega_b I) IQ(I)$$
Frequency termination point:

$$H_T \to 0$$
Bifurcation point:

$$H_T \to 0 \quad \Omega_b \to 1$$

Four Regimes of Solutions





Self-Consistent Perturbative Analysis

Perturbed equations for the mode's phase and amplitude

and

Linearized Vlasov equation

$$\frac{D\delta f}{Dt} = \dot{\xi} \frac{\partial \delta \varphi}{\partial \xi} \frac{\partial F(E)}{\partial E} = \frac{\partial F(E)}{\partial E} \left(\frac{D}{Dt} - \frac{\partial}{\partial t} \right) \delta \varphi \qquad \qquad \frac{D}{Dt} = \frac{\partial}{\partial t} + \dot{\xi} \frac{\partial}{\partial \xi} - \frac{\partial H_0}{\partial \xi} \frac{\partial}{\partial \dot{\xi}}$$

Perturbation of the distribution function:

$$\delta f = \frac{\partial F(E)}{\partial E} \left[\delta \varphi(\xi, t) - \int_{-\infty}^{t} dt' \frac{\partial}{\partial t'} \delta \varphi(\xi, t') \right]$$
$$\delta \varphi(\xi, t) \approx -\Delta A \cos(\xi) - \Delta \alpha A_0 \sin(\xi)$$

Integration along unperturbed trajectories

[Eremin, Berk, Phys. Plasmas (2004)]

Dispersion Relation for the Perturbed Eigenmodes

$$\begin{split} \omega^2 D_2 \left(\omega^2 \right) &= D_1 + \frac{A_0}{\Delta \omega D_3 \left(\omega^2 \right)} \\ D_1 &= \Delta \omega \left[1 - \beta \int_{-A_0}^{A_0} dE \frac{1}{\Delta \omega} \frac{\partial G(E)}{\partial E} T(E) \left[\left\langle \cos^2(\xi) \right\rangle_0^c - \left(\left\langle \cos(\xi) \right\rangle_0^c \right)^2 \right] \right] \\ D_2 &= 2\beta \int_{-A_0}^{A_0} dE \frac{\partial G(E)}{\partial E} T(E) \sum_{p=1}^{\infty} \left[\frac{\left(\left\langle \cos(\xi) \right\rangle_{2p}^c \right)^2}{\left(2p\omega_b(E) \right)^2 - \omega^2} \right] \\ D_3 &= 2\beta A_0 \int_{-A_0}^{A_0} dE \frac{1}{\Delta \omega} \frac{\partial G(E)}{\partial E} T(E) \sum_{p=1}^{\infty} \left[\frac{\left(\left\langle \sin(\xi) \right\rangle_{2p-1}^c \right)^2}{\left((2p-1)\omega_b(E) \right)^2 - \omega^2} \right] \end{split}$$

$$A_0^{1/2} / \Delta \omega \ll 1 \qquad \gamma^2 D_2 \left(-\gamma^2 \right) = -D_1 \qquad \gamma \equiv -i\omega$$

If $\frac{\partial G}{\partial E} > 0$ then lhs is positive, $\gamma^2 D_2(-\gamma^2) = 2\beta\gamma^2 \int_{-A_0}^{A_0} dE \frac{\partial G(E)}{\partial E} T(E) \sum_{p=1}^{\infty} \left[\frac{\left(\left\langle \cos(\xi) \right\rangle_{2p}^c \right)^2}{\left(2p\omega_b(E) \right)^2 + \gamma^2} \right] > 0$ $\gamma^2 D_2(-\gamma^2) \xrightarrow{\gamma \to \infty} 2\beta \int_{-A_0}^{A_0} dE \frac{\partial G(E)}{\partial E} T(E) \sum_{p=1}^{\infty} \left(\left\langle \cos(\xi) \right\rangle_{2p}^c \right)^2 \equiv D > 0$

Unstable root guaranteed if $D_1 < 0$

After a great deal of algebraic manipulations, we find that $D_1 = \frac{H_T}{2}$

$$A_0^{1/2} / \Delta \omega \ll 1 \qquad \gamma^2 D_2 \left(-\gamma^2 \right) = -D_1 \qquad \gamma \equiv -i\omega$$

If $\frac{\partial G}{\partial E} > 0$ then lhs is positive, $\gamma^2 D_2(-\gamma^2) = 2\beta\gamma^2 \int_{-A_0}^{A_0} dE \frac{\partial G(E)}{\partial E} T(E) \sum_{p=1}^{\infty} \left[\frac{\left(\left\langle \cos(\xi) \right\rangle_{2p}^c \right)^2}{\left(2p\omega_b(E) \right)^2 + \gamma^2} \right] > 0$ $\gamma^2 D_2(-\gamma^2) \xrightarrow{\gamma \to \infty} 2\beta \int_{-A_0}^{A_0} dE \frac{\partial G(E)}{\partial E} T(E) \sum_{p=1}^{\infty} \left(\left\langle \cos(\xi) \right\rangle_{2p}^c \right)^2 \equiv D > 0$

Unstable root guaranteed if $D_1 < 0$

After a great deal of algebraic manipulations, we find that $D_1 = \frac{H_T}{2}$

⇒ Adiabatic theory "knows" about onset of the instability!

Numerical Results: Dynamic Run



Comparison of predicted evolution with particle simulation for a case when a frequency termination point is reached.

$$\omega_{bi} = 0.011, \gamma_d / \omega_{bi} = 0.37, I_* = 0.8$$

 $\Delta I = 0.02, \Delta \omega_0 / \omega_{bi} = 18.5$

Self-Consistent Dynamics of Multiple Structures



Mutual Interaction between Multiple Structures

Mechanisms for Amplitude Reduction



Mutual Interaction between Multiple Structures

Summary

• Nonlinear phase space structures occur spontaneously in a resonant system with damping, close to instability threshold.

- The adiabatic analysis very accurately describes the frequency sweeping when the mode is stable.
- The self-consistent adiabatic solution may evolve to points, where the adiabatic analysis fails.

• Linear perturbative analysis demonstrates that these points are exactly where an instability is triggered.



• Nonlinear response interesting, needs further study.

• Generation of subsidiary structures changes mode amplitude; analytic prediction successfully made.

• Theoretical arguments considered here should be important in understanding the experimental data.